

# 多元函数

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## 极限

白话：以何种方式趋向某点，极限都存在且相同

$f(x,y) = \frac{xy}{x^2+y^2}$  在  $(x,y) \rightarrow (0,0)$  时无极限

令  $x = \rho \cos \theta, y = \rho \sin \theta, (x,y) \rightarrow (0,0) \Leftrightarrow \rho \rightarrow 0^+$

当  $\rho$  沿  $L: x = \rho \cos \theta_0, y = \rho \sin \theta_0$  趋向于  $(0,0)$  时

$$\lim_{\substack{x,y \in L \\ (x,y) \rightarrow (0,0)}} f(x,y) = \lim_{\rho \rightarrow 0^+} \cos \theta_0 \sin \theta_0 = \cos \theta_0 \sin \theta_0$$

## 偏导

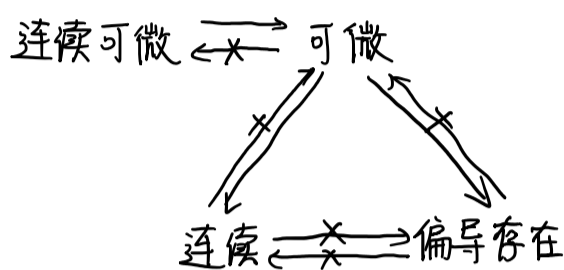
一元函数 可导  $\Rightarrow$  连续

二元函数 可偏导  $\xrightarrow{\text{各偏导数邻域内有界}}$  连续

连续  $\not\Rightarrow$  偏导存在

可微  $\not\Rightarrow$  连续可微

可微  $\Rightarrow$  连续  
可微  $\Rightarrow$  可偏导



## 极值

对各变量是极值点

可偏导, 偏导为0  $\Rightarrow$  驻点  $\xrightarrow{\text{判别法}}$  极值点

设函数  $f(x) = f(x_1, x_2, \dots, x_n)$  在点  $a = (a_1, \dots, a_n)$  邻近至少是二阶连续可微的。

考查由  $f$  在点  $a$  的二阶偏导数组成的方阵

$$H_f(a) = \begin{pmatrix} \frac{\partial^2 f}{\partial x_1^2}(a) & \frac{\partial^2 f}{\partial x_1 \partial x_2}(a) & \dots & \frac{\partial^2 f}{\partial x_1 \partial x_n}(a) \\ \frac{\partial^2 f}{\partial x_2 \partial x_1}(a) & \frac{\partial^2 f}{\partial x_2^2}(a) & \dots & \frac{\partial^2 f}{\partial x_2 \partial x_n}(a) \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f}{\partial x_n \partial x_1}(a) & \frac{\partial^2 f}{\partial x_n \partial x_2}(a) & \dots & \frac{\partial^2 f}{\partial x_n^2}(a) \end{pmatrix}$$

正定  $\Rightarrow$  严格极小

负定  $\Rightarrow$  严格极大

极坐标换元

$$(x(\rho, \theta), y(\rho, \theta)) = (\rho \cos \theta, \rho \sin \theta)$$

$$\frac{D(x,y)}{D(\rho, \theta)} = \begin{vmatrix} \cos \theta & -\rho \sin \theta \\ \sin \theta & \rho \cos \theta \end{vmatrix} = \rho \geq 0$$

## 二重积分

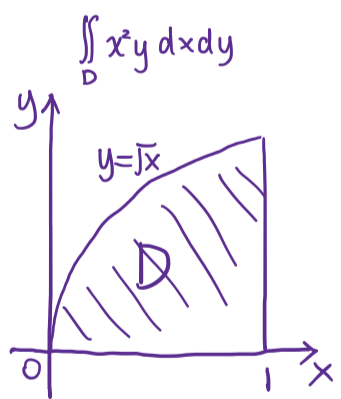
累次

换元

$$\begin{cases} x = x(u,v) \\ y = y(u,v) \end{cases}$$

$$\iint_D f(x,y) dx dy$$

$$= \iint_E f(x(u,v), y(u,v)) \left| \frac{\partial(x,y)}{\partial(u,v)} \right| d(u,v)$$



• 先对 y 积

$$D = \{(x,y) | x \in [0,1], 0 \leq y \leq \sqrt{x}\}$$

$$\begin{aligned} \iint_D x^2 y dx dy &= \int_0^1 \left( \int_0^{\sqrt{x}} x^2 y dy \right) dx \\ &= \int_0^1 \left( x^2 \frac{y^2}{2} \Big|_{y=0}^{y=\sqrt{x}} \right) dx \\ &= \int_0^1 x^2 \frac{x}{2} dx \\ &= \frac{1}{8} \end{aligned}$$

• 先对 x 积

$$D = \{(x,y) | y \in [0,1], y^2 \leq x \leq 1\}$$

$$\begin{aligned} \iint_D x^2 y dx dy &= \int_0^1 \left( \int_{y^2}^1 x^2 dx \right) dy \\ &= \int_0^1 \left( y \frac{x^3}{3} \Big|_{x=y^2}^{x=1} \right) dy \\ &= \int_0^1 y \left( \frac{1}{3} - \frac{y^6}{3} \right) dy \\ &= \frac{1}{8} \end{aligned}$$

## 三重积分

累次

换元

$$\begin{cases} x = x(u,v,w) \\ y = y(u,v,w) \\ z = z(u,v,w) \end{cases}$$

$$J(u,v,w) = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix}$$

柱坐标变换

$$x = \rho \cos \theta$$

$$y = \rho \sin \theta$$

$$z = z$$

$$J(\rho, \theta, z) = \rho \geq 0$$

球坐标变换

$$x = r \sin \theta \cos \varphi$$

$$y = r \sin \theta \sin \varphi$$

$$z = r \cos \theta$$

$$J(r, \theta, \varphi) = r^2 \sin \theta \geq 0$$

$$\iiint_{\Omega} y dx dy dz$$

$$D = \{(x,y) | 0 \leq x \leq 1-y, 0 \leq y \leq 1\}$$

$$\Omega = \{(x,y,z) | (x,y) \in D, 0 \leq z \leq 1-x-y\}$$

$$\begin{aligned} \iiint_{\Omega} y dx dy dz &= \iint_D \left( \int_0^{1-x-y} y dz \right) dx dy \\ &= \iint_D y(1-x-y) dx dy = \int_0^1 \left( \int_0^{1-y} y(1-x-y) dx \right) dy \\ &= \int_0^1 \left( -\frac{1}{2} x^2 + (y-y^2)x \Big|_{x=0}^{x=1-y} \right) dy = \int_0^1 \frac{1}{2} y(1-y^2) dy \\ &= \frac{1}{8} y^4 - \frac{1}{3} y^3 + \frac{1}{4} y^2 \Big|_0^1 = \frac{1}{24} \end{aligned}$$

